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Features and Benefits

- Built-in pre-drive IC
- MOSFET power element
- Alleviate noise generation by adjusting an internal resistor
- CMOS compatible input (5 V)
- High-side gate driver using bootstrap circuit or floating power supply
- Built-in protection circuit for controlling power supply voltage drop (UVLO on VB and VCC)
- Overcurrent protection (OCP), overcurrent limiting (OCL), and thermal shutdown (TSD)
- Output of fault signal during operation of protection circuit
- Output current 1.5, 2, or 2.5 A
- Small SIP (SMA 24-pin)

Packages: Power SIP



Description

The SMA6860MZ inverter power module (IPM) series provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take 230 VAC input voltage, and up to 2.5 A (continuous) output current. They can withstand voltages of up to 500 V (MOSFET breakdown voltage).

The SMA6860MZ power package includes an IC with all of the necessary power elements (six MOSFETs), pre-driver ICs (two), and bootstrap diodes (three), needed to configure the main circuit of an inverter. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- Air conditioner fan
- Small ventilation fan
- · Dishwasher pump

Functional Block Diagram



B. SD1, SD2 and OCL terminals are open-collector output. RC terminal is open-drain output. C. Blanking Time (t_{blank}) is used in Overcurrent Limiting (OCL) and Overcurrent Protection (OCP) If the time exceeds the limit, the signal will be output (open-collector output turns on) on the SD2 pin, and protection operation will start up.

Figure 1. Driver block diagram

Selection Guide

	MOSFET Breakdown	Output	Current
Part Number	Voltage, V _{DSS} (min) (V)	Continuous, I _O (max) (A)	Pulsed, I _{OP} (max) (A)
SMA6861MZ	250	2	3.0
SMA6862MZ	500	1.5	2.25
SMA6863MZ	500	2.5	3.75
SMA6864MZ	250	2.5	3.75
SMA6865MZ	500	2.5	3.75

Absolute Maximum Ratings, valid at T_A = 25°C

Characteristic	Symbol		Remarks	Rating	Unit
		SMA6861MZ		250	V
		SMA6862MZ		500	V
MOSFET Breakdown Voltage	V _{DSS}	SMA6863MZ	V _{CC} = 15 V, I _D = 100 μA, V _{IN} = 0 V	500	V
		SMA6864MZ		250	V
		SMA6865MZ		500	V
Logic Supply Voltage	V _{CC}	Between VCC a	and COM	20	V
Bootstrap Voltage	V _{BS}	Between VB an	d HS (U,V, and W phases)	20	V
		SMA6861MZ		2	A
		SMA6862MZ		1.5	A
Output Current, Continuous	lo	SMA6863MZ		2.5	A
		SMA6864MZ		2.5	A
		SMA6865MZ		2.5	A
		SMA6861MZ		3.0	A
		SMA6862MZ		2.25	A
Output Current, Pulsed	I _{OP}	SMA6863MZ	PW ≤ 100 µs, duty cycle = 1%	3.75	A
		SMA6864MZ		3.75	A
		SMA6865MZ		3.75	A
Input Voltage	V _{IN}	HINx and LINx	pins	-0.5 to 7	V
Pull-up Voltage for Shutdown Pins	V _{SDX}	SDx pins		7	V
Pull-up Voltage for Overcurrent Limiting Pin	V _{OCL}			7	V
Allowable Power Dissipation	PD	T _C = 25°C		28	W
Thermal Resistance (Junction to Case)	R _{θJC}	All elements op	erating	4.46	°C/W
Thermal Resistance (Junction to Ambient)	R _{0JA}	All elements op	erating	31.25	°C/W
Case Operating Temperature	T _{COP}			-20 to 100	°C
Storage Temperature	T _{stg}			-40 to 150	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature, T_A , of 25°C, unless otherwise stated.

Recommended Operating Conditions

Characteristic	Symbol		Remarks	Min.	Тур.	Max.	Units
		SMA6861MZ		-	-	200	V
		SMA6862MZ		-	-	400	V
Main Supply Voltage	V_{BB}	SMA6863MZ	Between VBB and LS	-	-	400	V
		SMA6864MZ	_	_	_	200	V
		SMA6865MZ			_	400	V
V _{BB} Snubber Capacitor	C _{SB}			0.01	_	0.1	μF
Logic Supply Voltage	V _{CC}	Between VCC and	СОМ	13.5	15	16.5	V
Zener Voltage for VCCx Pins	Vz	Between VCC and	COM	18	-	20	V
Pull-up Voltage	$V_{SDx,}V_{OCL}$			4.5	5	5.5	V
Pull-up Resistor $\overline{SD2}$ Pin	R _{UP2}			3.3	-	10	kΩ
Pull-up Resistor OCL Pin	R _{UP1}			1	-	10	kΩ
Pull-up Resistor RC Pin	R _R			33	-	390	kΩ
Capacitor $\overline{\text{SDx}}$ and $\overline{\text{OCL}}$ Pins	C_{SDX}			1	-	10	nF
Capacitor RC Pin	C _C			1	-	4.7	nF
Dead Time	t _{dead}	$T_{\rm J} = -20^{\circ} \text{C} \text{ to } 150^{\circ}$	°C	1.5	-	_	μs
Minimum Input Pulse Width	I _{INMIN(on)}	$T_{\rm J} = -20^{\circ} \text{C} \text{ to } 150^{\circ}$	О°С	0.5	-	-	μs
	I _{INMIN(off)}	$T_{\rm J} = -20^{\circ} \text{C} \text{ to } 150^{\circ}$	°C	0.5	-	-	μs
Switching Frequency	f _{PWM}			-	-	20	kHz

Typical Application Diagram



NOTE:

The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise susceptibility is necessary.

Typical Application Diagram

Shows configuration without current limiter function: SD1 and SD2 pins tied together



NOTE:

The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise susceptibility is necessary.

High Voltage 3-Phase Motor Drivers

ELECTRICAL CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol		Conditions	Min	Тур	Max	Units
Logic Supply Current	I _{CC}	V _{CC} = 15 V, T _C	; = −20°C to 125°C	_	2.7	5.0	mA
Bootstrap Supply Current	I _{BX}	V _{BX} = 15 V, V _H	$IIN = 5 \text{ V}, \text{ T}_{\text{C}} = -20^{\circ}\text{C} \text{ to } 125^{\circ}\text{C}$	_	135	380	μA
	VIH	V _{CC} = 15 V		_	2.9	3.4	V
Input Voltage	VIL	V _{CC} = 15 V		1.6	2.1	_	V
Input Voltage Hysteresis	V _{lhys}	V _{CC} = 15 V		_	0.8	_	V
Input Current	I _{IN}	V _{IN} = 5 V		_	230	500	μA
	V _{UVHL}			9.0	10.0	11.0	V
	V _{UVHH}	High side, bet	veen VBx and U, V, or W	9.5	10.5	11.5	V
Understation and a study of the	V _{UVHhys}	High side, hys	teresis	_	0.5	_	V
Undervoltage Lock Out	V _{UVLL}		N/222 1 221/2	10.0	11.0	12.0	V
	V _{UVLH}	Low side, betw	veen VCC2 and COM2	10.5	11.5	12.5	V
	V _{UVLhys}	Low side, hyst	eresis	_	0.5	_	V
SDx and OCLOutput Voltage	V _{SDX(on)} , V _{OCL}	V _{SDX} = V _{OCL} =	5 V, R _{UPX} = 3.3 kΩ	-	_	0.6	V
Overtemperature DetectionThreshold	T _{DH}			120	135	150	°C
Temperature (Activation and	T _{DL}	V _{CC} = 15 V, hig	gh-side and low side	100	115	130	°C
Deactivation)	T _{Dhys}			_	20	_	°C
Overcurrent Protection Trip Voltage	V _{TRIP}	V _{CC} = 15 V		0.9	1.0	1.1	V
Overcurrent Limit Reference Voltage	V _{LIM}	V _{CC} = 15 V		0.5035	0.53	0.5565	V
Overcurrent Protection Hold Time	tp	V _{RC} = 5 V, R _R	= 360 kΩ, C _C = 0.0047 μF	_	2.0	-	ms
Blanking Time	t _{blank}	V _{CC} = 15 V		_	2.0	_	μs
		SMA6861MZ	V _R = 250 V	_	_	10	μA
		SMA6862MZ	V _R = 500 V	_	-	10	μA
Bootstrap Diode Leakage Current	I _{LBD}	SMA6863MZ	V _R = 500 V	_	_	10	μA
		SMA6864MZ	V _R = 250 V	_	_	10	μA
		SMA6865MZ	V _R = 500 V	_	_	10	μA
Bootstrap Diode Forward Voltage	V _{FBD}	I _F = 0.05 A		_	0.8	1.3	V
Bootstrap Diode Recovery Time	t _{rrb}	I _F / I _{RP} = 100 n	nA / 100 mA	_	70	_	ns
Bootstrap Diode Series Resistor	R _{BD}			168	210	252	Ω
		SMA6861MZ		250	_	_	V
		SMA6862MZ		500	_	_	V
MOSFET Breakdown Voltage	V _{DSS}	SMA6863MZ	V_{CC} = 15 V, I _D = 100 µA, V _{IN} = 0 V	500	_	_	V
		SMA6864MZ			_	_	V
		SMA6865MZ		500	_	_	V
		SMA6861MZ	V_{CC} = 15 V, V_{DS} = 250 V, V_{IN} = 0 V	_	_	100	μA
		SMA6862MZ	V_{CC} = 15 V, V_{DS} = 500 V, V_{IN} = 0 V	_	_	100	μA
MOSFET Leakage Current	I _{DSS}	SMA6863MZ	V_{CC} = 15 V, V_{DS} = 500 V, V_{IN} = 0 V	_	_	100	μA
-		SMA6864MZ	V _{CC} = 15 V, V _{DS} = 250 V, V _{IN} = 0 V	_	_	100	μA
		SMA6865MZ	V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μA

Continued on the next page...

High Voltage 3-Phase Motor Drivers

ELECTRICAL CHARACTERISTICS (continued), valid at $T_A=25^{\circ}C$, unless otherwise noted

Characteristics	Symbol		Conditions	Min	Тур	Max	Units
		SMA6861MZ	V_{CC} = 15 V, I _D = 1.0 A, V _{IN} = 5 V	-	1.25	1.5	Ω
		SMA6862MZ	V_{CC} = 15 V, I _D = 0.75 A, V _{IN} = 5 V	-	3.2	4.0	Ω
MOSFET On State Resistance	R _{DS(on)}	SMA6863MZ	V_{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	-	2.0	2.4	Ω
		SMA6864MZ	V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	-	0.35	0.5	Ω
		SMA6865MZ	V_{CC} = 15 V, I_D = 1.25 A, V_{IN} = 5 V	-	1.4	1.7	Ω
		SMA6861MZ	V_{CC} = 15 V, I _D = 1.0 A, V _{IN} = 5 V	-	1.1	1.5	V
		SMA6862MZ	V_{CC} = 15 V, I _D = 0.75 A, V _{IN} = 5 V	-	1.1	1.5	V
MOSFET Diode Forward Voltage	V _{SDF}	SMA6863MZ	V_{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	-	1.1	1.5	V
		SMA6864MZ	V_{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	_	0.8	1.2	V
		SMA6865MZ	V_{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	-	1.0	1.5	V

High Voltage 3-Phase Motor Drivers

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		-	660	-	ns
	t _{rH}		-	25	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 150 V, V_{CC} = 15 V, I_D = 2.0 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	50	-	ns
	t _{dH(off)}		-	560	-	ns
	t _{fH}	-		10	-	ns
	t _{dL(on)}		-	540	-	ns
	t _{rL}		-	25	-	ns
Switching Time, Low Side	t _{rrL}	V_{BB} = 150 V, V_{CC} = 15 V, I_D = 2.0 A, 0 V ≤ V_{IN} ≤ 5 V , inductive load	-	45	-	ns
	t _{dL(off)}		-	500	_	ns
	t _{fL}		-	15	_	ns

SMA6861MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

SMA6862MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Мах	Units
	t _{dH(on)}		-	720	_	ns
	t _{rH}		-	60	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 1.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	110	-	ns
	t _{dH(off)}		-	690	-	ns
	t _{fH}		-	30	-	ns
	t _{dL(on)}		-	670	_	ns
	t _{rL}		-	70	-	ns
Switching Time, Low Side	t _{rrL}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 1.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	120	-	ns
	t _{dL(off)}		-	590	-	ns
	t _{fL}		-	30	-	ns

SMA6863MZ SWITCHING CHARACTERISTICS, valid at TA=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Мах	Units
	t _{dH(on)}		-	820	-	ns
	t _{rH}		-	100	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	120	-	ns
	t _{dH(off)}		-	740	-	ns
	t _{fH}		-	30	-	ns
	t _{dL(on)}		-	790	-	ns
	t _{rL}		-	110	-	ns
Switching Time, Low Side	t _{rrL}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	130	-	ns
	t _{dL(off)}		-	700	-	ns
	t _{fL}		-	30	-	ns

High Voltage 3-Phase Motor Drivers

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		-	730	-	ns
	t _{rH}		-	40	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 150 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	75	-	ns
	t _{dH(off)}		-	640	-	ns
	t _{fH}		-	20	-	ns
	t _{dL(on)}		-	660	-	ns
	t _{rL}		-	40	-	ns
Switching Time, Low Side	t _{rrL}	V_{BB} = 150 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	55	-	ns
	t _{dL(off)}		-	600	-	ns
	t _{fL}		-	30	_	ns

SMA6864MZ SWITCHING CHARACTERISTICS, valid at $T_A {=} 25^{\circ} \text{C},$ unless otherwise noted

SMA6865MZ SWITCHING CHARACTERISTICS, valid at $T_A=25^{\circ}C$, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Мах	Units
	t _{dH(on)}		-	750	-	ns
	t _{rH}		-	60	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	100	-	ns
	t _{dH(off)}		-	680	-	ns
	t _{fH}		-	20	-	ns
	t _{dL(on)}		-	640	-	ns
	t _{rL}		-	65	-	ns
Switching Time, Low Side	t _{rrL}	V_{BB} = 300 V, V_{CC} = 15 V, I_D = 2.5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	100	-	ns
	t _{dL(off)}		-	560	-	ns
	t _{fL}		-	20	-	ns



Switching Characteristics Definitions

High Voltage 3-Phase Motor Drivers

Mode	Hin	Lin	H-side MOSFET	L-side MOSFET
	L	L	Off	Off
Normal	Н	L	On	Off
Normai	L	Н	Off	On
	Н	Н	On	On
	L	L	Off	Off
TSD	Н	L	On	Off
150	L	Н	Off	Off
	Н	Н	On	Off
	L	L	Off	Off
OCP	Н	L	On	Off
UCP	L	Н	Off	Off
	Н	Н	On	Off
	L	L	Off	Off
$O(1/-1)^{1}$	Н	L	Off	Off
OCL (= L) ¹	L	Н	Off	On
	Н	Н	Off	On
	L	L	Off	Off
	Н	L	Off	Off
UVLO (VCC) ²	L	Н	Off	Off
	Н	Н	Off	Off
	L	L	Off	Off
	Н	L	Off	Off
UVLO (VB) ³	L	Н	Off	On
	Н	Н	Off	On
	L	L	Off	Off
	Н	L	On	Off
SD2 (= L)	L	Н	Off	Off
	Н	Н	On	Off

Truth Table

¹The OCL feature is enabled when the OCL and SD1 pins are tied together externally. If these pins are not tied when an OCL condition occurs, device operation continues in Normal mode.

 2 Returning to the Normal mode of operation from a V_{CC} UVLO condition, a high-side MOSFET resumes switching on the rising edge of an HINx input. On the other hand, a low-side MOSFET resumes switching on the first logic high of a LINx input after release of the UVLO condition.

 3 Returning to the Normal mode of operation from a V_B UVLO condition, a high-side MOSFET resumes switching on the rising edge of an HINx input.

Note: To prevent a shoot-through condition, the external microcontroller should not drive HINx = LINx = H at the same time.

High Voltage 3-Phase Motor Drivers



Low-Side Logic TSD Timing Diagram



High-Side UVLO Timing Diagram



Low-Side UVLO Timing Diagram





OCL and SD1 pins connected externally; current-limiter function in use



(a) Each HINx or LINx pin drives a independent side of a phase, that is, the high-side and the low-side swtiching devices of a U, V, or W motor coil phase are each driven separately, by the corresponding dedicated HINx or LIN;

Shut Down Timing Diagram

SD1 and SD2 pins connected externally; current-limiter function not in use



(a) Each HINx or LINx pin drives a independent side of a phase, that is, the high-side and the low-side swtiching devices of a U, V, or W motor coil phase are each driven separately, by the corresponding dedicated HINx or LINx input

Pin-out Diagrams



Chamfer on Opposite Side

Terminal List Table

Number	Name	Function
1	VB1	High side bootstrap terminal (U phase)
2	VB2	High side bootstrap terminal (V phase)
3	VB3	High side bootstrap terminal (W phase)
4	VCC1	High side logic supply voltage
5	SD1	High side shutdown input and UVLO fault signal output
6	COM1	High side logic GND terminal
7	HIN3	High side input terminal (W phase)
8	HIN2	High side input terminal (V phase)
9	HIN1	High side input terminal (U phase)
10	VBB	Main supply voltage
11	W1	Output of W phase (connect to W2 externally)
12	V	Output of V phase
13	W2	Output of W phase (connect to W1 externally)
14	LS2	Low side source terminal (connect to LS1 externally)
15	RC	Overcurrent protection hold time adjustment input terminal
16	LS1	Low side source terminal (connect to LS2 externally)
17	OCL	Output for overcurrent limiting
18	LIN3	Low side input terminal (W phase)
19	LIN2	Low side input terminal (V phase)
20	LIN1	Low side input terminal (U phase)
21	COM2	Low side GND terminal
22	SD2	Low side shutdown input and overtemperature, overcurrent, and UVLO fault signals output
23	VCC2	Low side logic supply voltage
24	U	Output of U phase

Leadform 2452



Package Outline Drawing

Leadform 2451

Dual rows, 24 alternating pins; pins bent 90° for horizontal case mounting; pin #1 in outer row





Leadframe plating Pb-free. Device composition complies with the RoHS directive.

High Voltage 3-Phase Motor Drivers

Package Outline Drawing

Leadform 2452

Dual rows, 24 alternating pins; vertical case mounting; pin #1 opposite chamfer side



Pb

Leadframe plating Pb-free. Device composition complies with the RoHS directive.

High Voltage 3-Phase Motor Drivers

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product on a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the product.
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated below:

Туре	Suppliers
G746	Shin-Etsu Chemical Co., Ltd.
YG6260	Momentive Performance Materials
SC102	Dow Corning Toray Silicone Co., Ltd.

Soldering

- When soldering the products, please be sure to minimize the working time, within the following limits:
 260±5°C 10 s
 280±5°C 5 c
 - 380±5°C 5 s
- Soldering iron should be at a distance of at least 1.5 mm from the body of the products

Electrostatic Discharge

- When handling the products, operator must be grounded. Grounded wrist straps worn should have at least 1 M Ω of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.

- The contents in this document are subject to changes, for improvement and other purposes, without notice. Make sure that this is the latest revision of the document before use.
- Application and operation examples described in this document are quoted for the sole purpose of reference for the use of the products herein and Sanken can assume no responsibility for any infringement of industrial property rights, intellectual property rights or any other rights of Sanken or any third party which may result from its use.
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- Sanken products listed in this document are designed and intended for the use as components in general purpose electronic equipment or apparatus (home appliances, office equipment, telecommunication equipment, measuring equipment, etc.).

When considering the use of Sanken products in the applications where higher reliability is required (transportation equipment and its control systems, traffic signal control systems or equipment, fire/crime alarm systems, various safety devices, etc.), and whenever long life expectancy is required even in general purpose electronic equipment or apparatus, please contact your nearest Sanken sales representative to discuss, prior to the use of the products herein.

The use of Sanken products without the written consent of Sanken in the applications where extremely high reliability is required (aerospace equipment, nuclear power control systems, life support systems, etc.) is strictly prohibited.

• In the case that you use Sanken products or design your products by using Sanken products, the reliability largely depends on the degree of derating to be made to the rated values. Derating may be interpreted as a case that an operation range is set by derating the load from each rated value or surge voltage or noise is considered for derating in order to assure or improve the reliability. In general, derating factors include electric stresses such as electric voltage, electric current, electric power etc., environmental stresses such as ambient temperature, humidity etc. and thermal stress caused due to self-heating of semiconductor products. For these stresses, instantaneous values, maximum values and minimum values must be taken into consideration.

In addition, it should be noted that since power devices or IC's including power devices have large self-heating value, the degree of derating of junction temperature affects the reliability significantly.

- When using the products specified herein by either (i) combining other products or materials therewith or (ii) physically, chemically or otherwise processing or treating the products, please duly consider all possible risks that may result from all such uses in advance and proceed therewith at your own responsibility.
- Anti radioactive ray design is not considered for the products listed herein.
- Sanken assumes no responsibility for any troubles, such as dropping products caused during transportation out of Sanken's distribution network.
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