

# MP2234S High-Efficiency, 2A, 16V, 800kHz Synchronous, Step-Down Converter

The Future of Analog IC Technology

# DESCRIPTION

The MP2234S is a high-frequency, synchronous, rectified, step-down, switch-mode converter with built-in power MOSFETs. It offers a compact solution to achieve a 2A continuous output current with excellent load and line regulation over a wide input-supply range. The MP2234S has synchronous mode operation for higher efficiency over the output current load range.

Current-mode operation provides fast transient response and eases loop stabilization.

Full protection features include over-current protection (OCP) and thermal shut down (TSD).

The MP2234S requires a minimal number of readily-available standard external components, and is available in a space-saving 8-pin TSOT23 package.

**TYPICAL APPLICATION** 

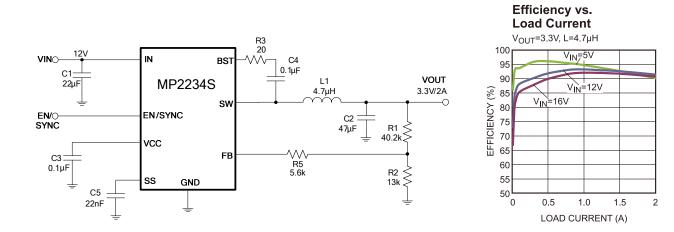
# FEATURES

- Wide 4.5V-to-16V Operating Input Range
- 140m $\Omega$ /60m $\Omega$  Low R<sub>DS(ON)</sub> Internal Power MOSFETs
- High-Efficiency Synchronous Mode
   Operation
- Fixed 800kHz Switching Frequency
- Synchronizes from a 300kHz-to-2MHz External Clock
- Power-Save Mode at Light Load
- External Soft-Start
- Over Current Protection and Hiccup
- Thermal Shutdown
- Output Adjustable from 0.804V
- Available in a 8-pin TSOT-23 Package

## **APPLICATIONS**

- Notebook Systems and I/O Power
- Digital Set-Top Boxes
- Flat-Panel Television and Monitors
- Distributed Power Systems

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### **ORDERING INFORMATION**

Part Number*	Package	Top Marking
MP2234SGJ	TSOT-23	See Below

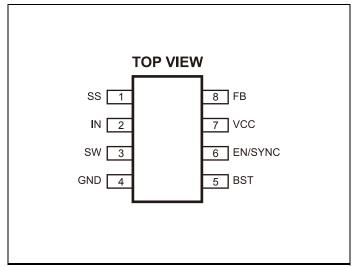
\* For Tape & Reel, add suffix –Z (e.g. MP2234SGJ–Z).

## **TOP MARKING**

## |ALZY

ALZ: product code of MP2234SGJ; Y: year code;

## PACKAGE REFERENCE





## ABSOLUTE MAXIMUM RATINGS (1)

Recommended Operating	Conditions <sup>(4)</sup>
Storage Temperature	65°C to 150°C
Lead Temperature	
Junction Temperature	
	1.25W
Continuous Power Dissipation	$(T_A = +25^{\circ}C)^{(3)}$
All Other Pins	
V <sub>BST</sub>	V <sub>SW</sub> +6V
-0.3V (-5V for <10ns) to 17	7V (19V for <10ns)
V <sub>SW</sub>	
V <sub>IN</sub>	

Supply Voltage V <sub>IN</sub>	0
Output Voltage Vout	
Operating Junction Temp.	

# Thermal Resistance $^{(5)}$ $\theta_{JA}$

TSOT23-8 ..... 100 ..... 55 ... °C/W

 $\theta_{JC}$ 

#### Notes:

- 1) Exceeding these ratings may damage the device.
- About the details of EN pin's ABS MAX rating, please refer to Page 12, Enable/SYNC control section.
- 3) The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub> (MAX), the junction-toambient thermal resistance  $\theta_{JA}$ , and the ambient temperature T<sub>A</sub>. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P<sub>D</sub> (MAX) = (T<sub>J</sub> (MAX)-T<sub>A</sub>)/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- 4) The device is not guaranteed to function outside of its operating conditions.
- 5) Measured on JESD51-7, 4-layer PCB.



## **ELECTRICAL CHARACTERISTICS**

 $V_{IN}$ =12V, T<sub>J</sub>=-40°C to +125°C<sup>(6)</sup>, typical value is tested at T<sub>J</sub>=+25°C, unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Our also Our at (Obut down)		V <sub>EN</sub> = 0V, T <sub>J</sub> =+25°C			1	μA
Supply Current (Shutdown)	I <sub>IN</sub>	V <sub>EN</sub> = 0V, T <sub>J</sub> =-40°C to +125°C			5	μA
Supply Current (Quiescent)	Ι <sub>q</sub>	V <sub>EN</sub> = 2V, V <sub>FB</sub> = 1V		0.5	1	mA
HS Switch-On Resistance	HS <sub>RDS-ON</sub>	V <sub>BST-SW</sub> =5V		140		mΩ
LS Switch-On Resistance	LS <sub>RDS-ON</sub>	V <sub>CC</sub> =5V		60		mΩ
Switch Leakage	SW <sub>LKG</sub>	$V_{EN}$ = 0V, $V_{SW}$ =12V or 0V			1	μA
Current Limit	I <sub>LIMIT</sub>	Under 40% Duty Cycle	3	4		Α
Oscillator Frequency	f	V <sub>FB</sub> =0.75V,T <sub>J</sub> =+25°C	620	800	900	kHz
Oscillator Frequency	f <sub>SW</sub>	V <sub>FB</sub> =0.75V,T <sub>J</sub> =-40°C to +125°C	550	800	900	kHz
Fold-Back Frequency	f <sub>FB</sub>	V <sub>FB</sub> <400mV		0.5		$f_{SW}$
Maximum Duty Cycle	D <sub>MAX</sub>	V <sub>FB</sub> =700mV		92		%
Minimum On Time <sup>(7)</sup>	T <sub>ON_MIN</sub>			40		ns
Sync Frequency Range	f <sub>SYNC</sub>		0.3		2	MHz
	V <sub>FB</sub>	T <sub>J</sub> =25°C	788	804	820	mV
Feedback Voltage		T <sub>J</sub> =-40°C to +125°C	784	804	824	mV
Feedback Current	I <sub>FB</sub>	V <sub>FB</sub> =830mV		10	50	nA
EN Rising Threshold	V <sub>EN_RISING</sub>		1	1.4	1.8	V
EN Hysteresis	V <sub>EN Hysteresis</sub>			150		mV
EN Input Current		V <sub>EN</sub> =2V		2		μA
	I <sub>EN</sub>	V <sub>EN</sub> =0		0		μA
EN Turn-Off Delay	EN <sub>td-off</sub>			10		μs
VIN Under-Voltage Lockout Threshold—Rising	INUV <sub>Vth</sub>		3.5	3.9	4.3	V
VIN Under-Voltage Lockout Threshold—Hysteresis	INUV <sub>HYS</sub>			700		mV
VCC Regulator	V <sub>CC</sub>		4.6	5	5.4	V
VCC Load Regulation		I <sub>cc</sub> =5mA		2		%
Soft-Start Current	I <sub>SS</sub>		8	11	14	μA
Thermal Shutdown (7)				150		°C
Thermal Hysteresis (7)				20		°C

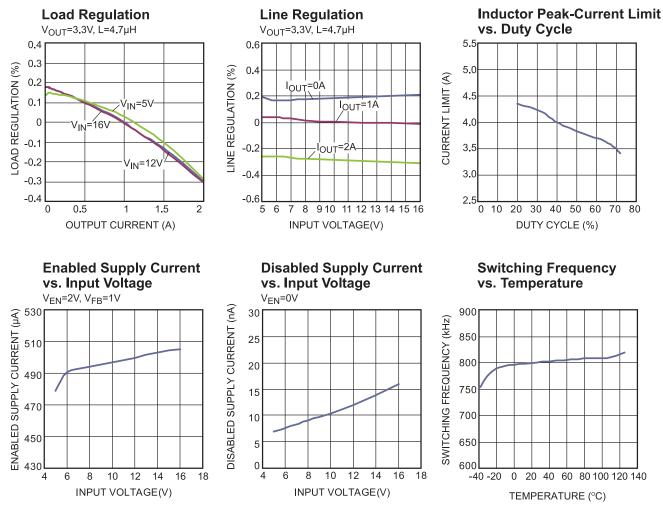
Notes:

6) Not tested in production. Guaranteed by over-temperature correlation.7) Guaranteed by design.

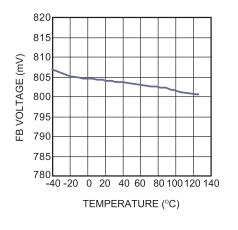


# **TYPICAL CHARACTERISTICS**

Performance waveforms are tested on the evaluation board of the Design Example section.  $V_{IN}$  = 12V,  $V_{OUT}$  = 3.3V, L=4.7µH,  $T_A$  = 25°C, unless otherwise noted.



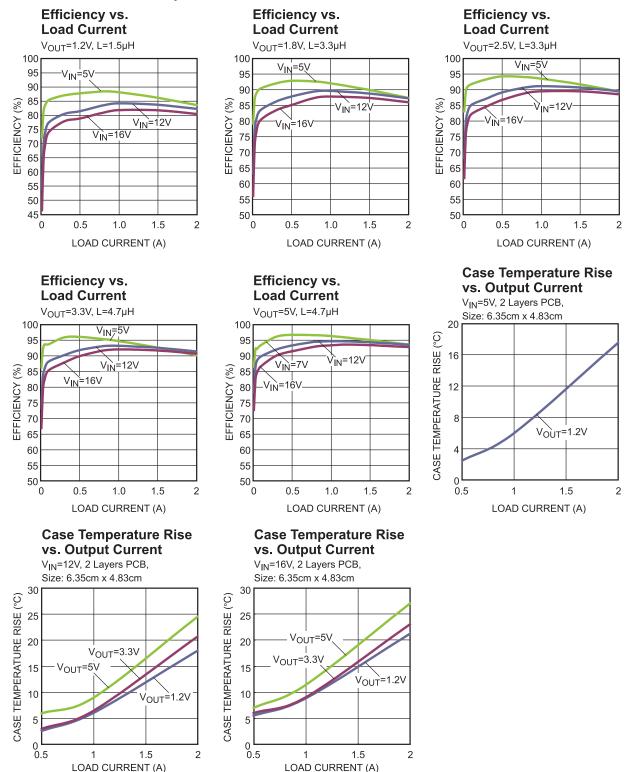
#### FB Voltage vs. Temperature





## **TYPICAL PERFORMANCE CHARACTERISTICS**

Performance waveforms are tested on the evaluation board of the Design Example section.  $V_{IN} = 12V$ ,  $V_{OUT} = 3.3V$ , L=4.7µH,  $T_A = 25^{\circ}$ C, unless otherwise noted.

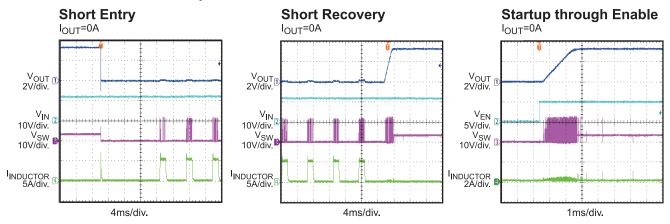


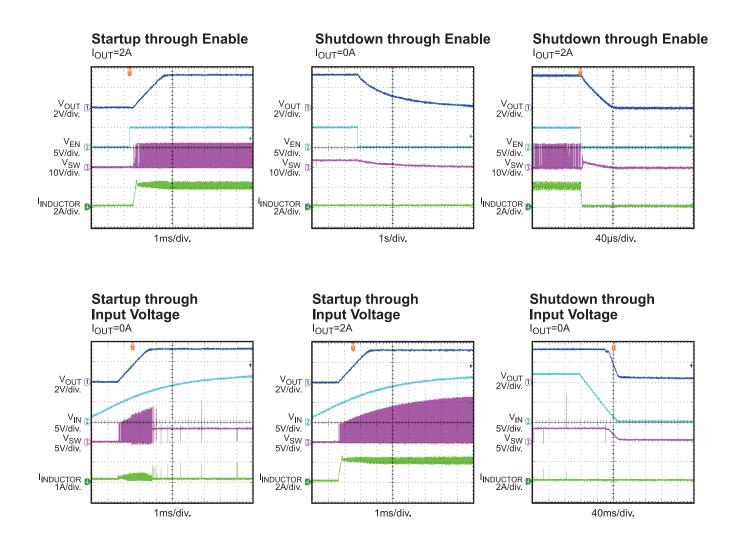
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## **TYPICAL PERFORMANCE CHARACTERISTICS** (contiuned)

Performance waveforms are tested on the evaluation board of the Design Example section.  $V_{IN} = 12V$ ,  $V_{OUT} = 3.3V$ , L=4.7µH,  $T_A = 25^{\circ}$ C, unless otherwise noted.

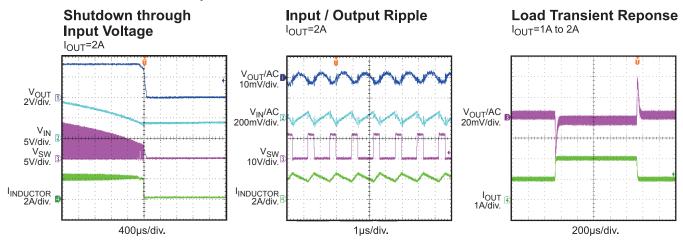






## **TYPICAL PERFORMANCE CHARACTERISTICS** (contiuned)

Performance waveforms are tested on the evaluation board of the Design Example section.  $V_{IN}$  = 12V,  $V_{OUT}$  = 3.3V, L=4.7µH,  $T_A$  = 25°C, unless otherwise noted.





# **PIN FUNCTIONS**

Package Pin #	Name	Description	
1	SS	Soft-Start. Connect an external capacitor to program the soft start time for the switch mode regulator.	
2	IN	Supply Voltage. The IN pin supplies power for internal MOSFET and regulator. Th MP2234S operates from a +4.5V to +16V input rail. Requires a low-ESR, and low inductance capacitor (C1) to decouple the input rail. Place the input capacitor very close t this pin and connect it with wide PCB traces and multiple vias.	
3	SW	Switch Output. Connect to the inductor and bootstrap capacitor. This pin is driven up to V <sub>1</sub> by the high-side switch during the PWM duty cycle ON time. The inductor current drive the SW pin negative during the OFF time. The ON resistance of the low-side switch an the internal body diode fixes the negative voltage. Connect using wide PCB traces an multiple vias.	
4	GND	System Ground. Reference ground of the regulated output voltage. PCB layout Require extra care. For best results, connect to GND with copper and vias.	
5	BST	Bootstrap. Requires a capacitor connected between SW and BST pins to form a floatin supply across the high-side switch driver.	
6	EN/SYNC	Enable/Synchronize. EN/SYNC=high to enable the MP2234S. Apply an external clo change the switching frequency. For automatic start-up, connect EN/SYNC pin to $V_{IN}$ w a 100k $\Omega$ resistor.	
7	VCC	C Internal 5V LDO output. Powers the driver and control circuits. Decouple with $0.1\mu$ F t 0.22µF capacitor. Do not use a capacitor ≥0.22µF.	
8	<ul> <li>Feedback. Connect to the tap of an external resistor divider from the output to GND to the output voltage. The frequency fold-back comparator lowers the oscillator freque when the FB voltage is below 400mV to prevent current limit runaway during a short cir fault. Place the resistor divider as close to the FB pin as possible. Avoid placing vias the FB traces.</li> </ul>		



FUNCTIONAL BLOCK DIAGRAM

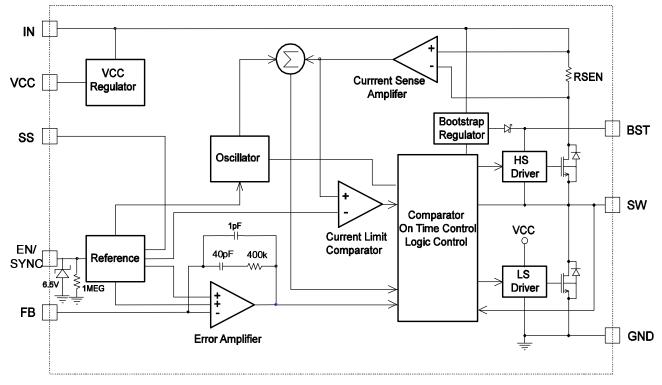


Figure 1. Functional Block Diagram



## **OPERATION**

The MP2234S is a high-frequency, synchronous, rectified, step-down, switch-mode converter with built-in power MOSFETs. It offers a compact solution that achieves a 2A continuous output current with excellent load and line regulation over 4.5V to 16V input-supply range.

The MP2234S has three working modes: advanced asynchronous modulation (AAM) mode, discontinuous conduction mode (DCM), and continuous conduction mode (CCM). The load current increases as the device transitions from AAM mode to DCM to CCM.

### **AAM** Control Operation

In a light-load condition, MP2234S works in advanced asynchronous modulation (AAM) mode (see Figure 2). The V<sub>AAM</sub> is an internal fixed voltage when input and output voltages are fixed.  $V_{COMP}$  is the error-amplifier output (which represents the peak inductor-current information). When  $V_{COMP}$  is lower than  $V_{AAM}$ , the internal clock is blocked. This causes the MP2234S to skip pulses, achieving the light-load power save. Refer to AN032 for additional details.

The internal clock re-sets every time  $V_{COMP}$  is higher than  $V_{AAM}$ . At the same time, the highside MOSFET (HS-FET) turns on and remains on until  $V_{ILsense}$  reaches the value set by  $V_{COMP}$ .

The light-load feature in this device is optimized for 12V input applications.

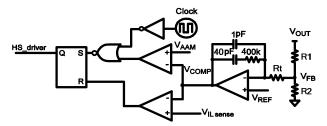


Figure 2. Simplified AAM Control Logic

### DCM Control Operation

The  $V_{COMP}$  voltage ramps up as the output current increases. When its minimum value exceeds  $V_{AAM}$ , the device enters discontinuous conduction mode (DCM). In DCM, the internal

clock initiates the PWM cycle, the HS-FET turns on and remains on until  $V_{ILsense}$  reaches the value set by  $V_{COMP}$  (after a period of dead time), and the low-side MOSFET (LS-FET) turns on and remains on until the inductor-current value decreases to zero. The device repeats the same operation in every clock cycle to regulate the output voltage (see Figure 3).

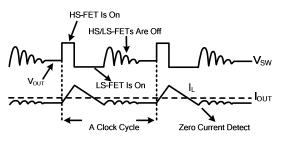


Figure 3. DCM Control Operation

### **CCM Control Operation**

The device enters continuous conduction mode (CCM) from DCM once the inductor current no longer drops to zero in a clock cycle. In CCM, the internal clock initiates the PWM cycle, the HS-FET turns on and remains on until  $V_{ILsense}$  reaches the value set by  $V_{COMP}$  (after a period of dead time), and the LS-FET turns on and remains on until the next clock cycle begins. The device repeats the same operation in every clock cycle to regulate the output voltage.

If  $V_{\text{ILsense}}$  does not reach the value set by  $V_{\text{COMP}}$  within 92% of one PWM period, the HS-FET is forced off.

### **Internal Regulator**

A 5V internal regulator powers most of the internal circuitries. This regulator takes  $V_{IN}$  and operates in the full  $V_{IN}$  range. When  $V_{IN}$  exceeds 5.0V, the output of the regulator is in full regulation. When  $V_{IN}$  is less than 5.0V, the output decreases, and the part requires a 0.1µF ceramic decoupling capacitor.

### Error Amplifier (EA)

The error amplifier compares the FB pin voltage to the internal 0.804V reference ( $V_{REF}$ ) and outputs a current proportional to the difference between the two. This output current then charges or discharges the internal compensation network to form the COMP voltage, which controls the power MOSFET current. The optimized internal compensation



network minimizes the external component counts and simplifies the control loop design.

### **Enable/SYNC Control**

EN/SYNC is a digital control pin that turns the regulator on and off. Drive EN high to turn on the regulator; drive it low to turn it off. An internal  $1M\Omega$  resistor from EN/SYNC to GND allows EN/SYNC to be floated to shut down the chip. The EN/SYNC pin is clamped internally using a 6.5V series-Zener-diode (see Figure 4). Connecting the EN/SYNC input pin through a pull-up resistor to the voltage on the IN pin limits the EN input current to less than  $100\mu$ A.

For example, with 12V connected to IN,  $R_{PULLUP} \ge (12V - 6.5V) \div 100\mu A = 55k\Omega$ .

Connecting the EN pin directly to a voltage source without any pull-up resistor requires limiting the amplitude of the voltage source to  $\leq 6V$  to prevent damage to the Zener diode.

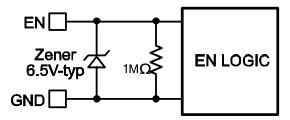


Figure 4. 6.5V Zener Diode Connection

For external clock synchronization, connect a clock with a frequency range between 300kHz and 2MHz 2ms after the output voltage is set: The internal clock rising edge will synchronize with the external clock rising edge. Select an external clock signal with a pulse width less than 1µs.

### Under-Voltage Lockout (UVLO)

The MP2234S has under-voltage lock-out protection (UVLO). When the VCC voltage exceeds the UVLO rising threshold voltage, the device begins to power-up. It shuts off when the VCC voltage drops below the UVLO falling threshold voltage. This is non-latch protection.

The MP2234S is disabled when the input voltage falls below 3.2V (Typ). If an application requires a higher under-voltage lockout (UVLO) threshold, use the EN pin to adjust the input voltage UVLO by using two external resistors

(see Figure 5). For best results, set the UVLO falling threshold (VSTOP) above 4.5V using the enable resistors. Set the rising threshold (VSTART) to provide enough hysteresis to allow for input-supply variations.

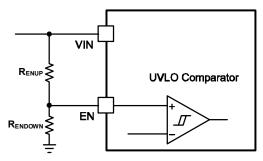


Figure 5. Adjustable UVLO

### Soft-Start (SS)

Adjust the soft-start time by connecting a capacitor from SS pin to ground. When the soft-start begins, an internal  $11\mu$ A current source charges the external capacitor. The soft-start capacitor connects to the non-inverting input of the error amplifier. The soft-start period continues until the voltage on the soft-start capacitor exceeds the 0.804V reference. Then the non-inverting amplifier takes the reference voltage as the input. Use the following equation to calculate the soft-start time:

$$t_{ss}(ms) = \frac{0.804V \times Css(nF)}{11\mu A}$$

### **Over-Current-Protection (OCP) and Hiccup**

The MP2234S has a cycle-by-cycle overcurrent limit when the inductor current peak value exceeds the set current limit threshold. Meanwhile, the output voltage drops until V<sub>FB</sub> is below the Under-Voltage (UV) threshold typically 50% below the reference. Once UV is triggered, the MP2234S enters hiccup mode to periodically restart the part. This protection mode is especially useful when the output is dead-shorted to ground, and greatly reduces the average short circuit current to alleviate thermal issues and protect the regulator. The MP2234S exits the hiccup mode once the overcurrent condition is removed.





### Thermal Shutdown (TSD)

Thermal shutdown prevents the chip from operating at exceedingly high temperatures. When the silicon die reaches temperatures that exceed 150°C, it shuts down the whole chip. When the temperature drops below its lower threshold, typically 130°C, the chip is enabled again.

### Floating Driver and Bootstrap Charging

An external bootstrap capacitor powers the floating power MOSFET driver. This floating driver has its own UVLO protection. This UVLO's rising threshold is 2.2V with a hysteresis of 150mV. The bootstrap capacitor voltage is regulated internally by V<sub>IN</sub> through D1, M1, R3, C4, L1 and C2 (see Figure 6). If (V<sub>IN</sub>-V<sub>SW</sub>) exceeds 5V, U1 will regulate M1 to maintain a 5V BST voltage across C4. A 20 $\Omega$  resistor placed between SW and BST cap is strongly recommended to reduce SW spike voltage.

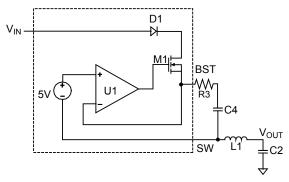


Figure 6. Internal Bootstrap Charging Circuit

#### Startup and Shutdown

If both  $V_{IN}$  and  $V_{EN}$  exceed their respective thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides a stable supply for the remaining circuitries.

Three events can shut down the chip:  $V_{EN}$  low,  $V_{IN}$  low and thermal shutdown. During the shutdown procedure, the signal path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

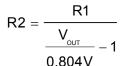


## APPLICATION INFORMATION

### Setting the Output Voltage

The external resistor divider sets the output voltage (see Typical Application on page 1).

Choose R1 around  $40k\Omega$  for V<sub>OUT</sub>>1.2V, R2 is then given by:



The T-Type network is recommended highly (see Figure 7)

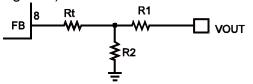


Figure 7. T-Type Network

Table 1 lists the recommended resistors and compensation values for common output voltages.

**Table 1: Resistor Selection for Common Output** Voltanes<sup>(8)</sup>

VUILayes			
V <sub>out</sub> (V)	R1 (kΩ)	R2 (kΩ)	Rt (kΩ)
1	20.5	84.5	34
1.2	30.1	61.9	24
1.8	40.2	32.4	15
2.5	40.2	19.1	6.8
3.3	40.2	13	5.6
5	40.2	7.68	2

#### Notes:

8) The recommended parameters are based on a 800kHz switching frequency; a different input voltage, output-inductor value, and output-capacitor value may affect the selection of R1, R2, and Rt. For additional component parameters, please refer to the "Typical Application Circuits" section on pages 17 and 18.

#### Selecting the Inductor

Use a 1µH-to-22µH inductor with a DC current rating of at least 25% percent higher than the maximum load current for most applications. For highest efficiency, use an inductor with a DC resistance less than  $15m\Omega$ . For most designs, the inductance value can be derived from the following equation.

$$L_{1} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_{I} \times f_{OSC}}$$

Where  $\Delta I_{L}$  is the inductor ripple current.

Choose the inductor ripple current to be approximately 30% of the maximum load current. The maximum inductor peak current is:

$$\mathsf{I}_{\mathsf{L}(\mathsf{MAX})} = \mathsf{I}_{\mathsf{LOAD}} + \frac{\Delta \mathsf{I}_{\mathsf{L}}}{2}$$

Use a larger inductor for improved efficiency under light-load conditions-below 100mA.

### Selecting the Input Capacitor

The input current to the step-down converter is discontinuous, therefore requires a capacitor is to supply the AC current to the step-down converter while maintaining the DC input voltage. Use low ESR capacitors for the best performance. Use ceramic capacitors with X5R or X7R dielectrics for best results because of their low ESR and small temperature coefficients. For most applications, use a 22µF capacitor.

Since C1 absorbs the input switching current, it requires an adequate ripple current rating. The RMS current in the input capacitor can be estimated by:

$$I_{C1} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

The worst case condition occurs at  $V_{IN} = 2V_{OUT}$ , where:

$$I_{C1} = \frac{I_{LOAD}}{2}$$

For simplification, choose an input capacitor with an RMS current rating greater than half of the maximum load current.

The input capacitor can be electrolytic, tantalum or ceramic. When using electrolytic or tantalum capacitors, add a small, high quality ceramic capacitor (e.g. 0.1µF) placed as close to the IC as possible. When using ceramic capacitors, make sure that they have enough capacitance provide sufficient charge to prevent to excessive voltage ripple at input. The input voltage ripple caused by capacitance can be estimated as:

$$\Delta V_{\text{IN}} = \frac{I_{\text{LOAD}}}{f_{\text{S}} \times C1} \times \frac{V_{\text{OUT}}}{V_{\text{IN}}} \times \left(1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}\right)$$

### Selecting the Output Capacitor

The output capacitor (C2) maintains the DC output voltage. Use ceramic, tantalum, or low-ESR electrolytic capacitors. For best results, use low ESR capacitors to keep the output voltage ripple low. The output voltage ripple can be estimated as:

$$\Delta V_{\text{OUT}} = \frac{V_{\text{OUT}}}{f_{\text{S}} \times L_{1}} \times \left(1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}\right) \times \left(R_{\text{ESR}} + \frac{1}{8 \times f_{\text{S}} \times C2}\right)$$

Where  $L_1$  is the inductor value and  $R_{ESR}$  is the equivalent series resistance (ESR) value of the output capacitor.

For ceramic capacitors, the capacitance dominates the impedance at the switching frequency, and the capacitance causes the majority of the output voltage ripple. For simplification, the output voltage ripple can be estimated as:

$$\Delta V_{\text{OUT}} = \frac{V_{\text{OUT}}}{8 \times f_{\text{S}}^{2} \times L_{1} \times C2} \times \left(1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}\right)$$

For tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated as:

$$\Delta V_{\text{out}} = \frac{V_{\text{out}}}{f_{\text{s}} \times L_{1}} \times \left(1 - \frac{V_{\text{out}}}{V_{\text{IN}}}\right) \times R_{\text{esr}}$$

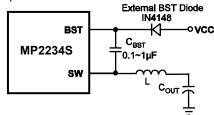
The characteristics of the output capacitor also affect the stability of the regulation system. The MP2234S can be optimized for a wide range of capacitance and ESR values.

### **External Bootstrap Diode**

In particular conditions, BST voltage may become insufficient (see equations below). During these conditions an external bootstrap diode can enhance the efficiency of the regulator and avoid insufficient BST voltage at light-load PFM operation. Insufficient BST voltage is more likely to occur during either of the following conditions:

- V<sub>OUT</sub> is 5V or 3.3V; and
- Duty cycle is high:  $D = \frac{V_{OUT}}{V_{IN}} > 65\%$

If the BST voltage is insufficient, the outputripple voltage may become extremely large during a light-load condition. If this occurs, add an external BST diode from VCC to BST (see Figure 8).



#### Figure 8. Optional External Bootstrap Diode to Enhance Efficiency

The recommended external BST diode is IN4148, and the BST capacitor value is  $0.1 \mu F$  to  $1 \mu F.$ 

### PC Board Layout<sup>(9)</sup>

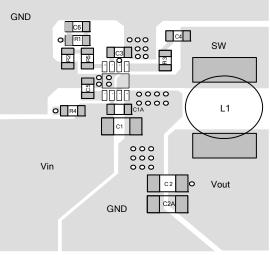
PCB layout is very important to achieve stable operation especially for VCC capacitor and input capacitor placement. For best results, refer to Figure 9 and the guidelines below:

- 1. Use large ground plane directly connect to GND pin. Add vias near the GND pin if bottom layer is ground plane.
- Place the VCC capacitor to VCC pin and GND pin as close as possible. Make the trace length of VCC pin-VCC capacitor anode-VCC capacitor cathode-chip GND pin as short as possible.
- Place the ceramic input capacitor close to IN and GND pins. Keep the connection of input capacitor and IN pin as short and wide as possible.
- 4. Route SW, BST away from sensitive analog areas such as FB.
- 5. Place the T-type feedback resistor R5 close to chip to ensure the trace which connects to FB pin as short as possible.

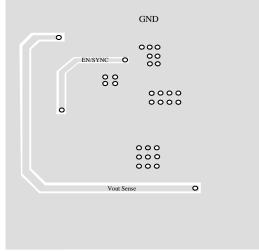
Notes:

 The recommended layout is based on the Figure 10 Typical Application circuit on page 17.









Bottom Layer Figure 9. Recommended PCB Layout

### **Design Example**

Below is a design example following the application guidelines for the specifications:

Table 2: Design Example

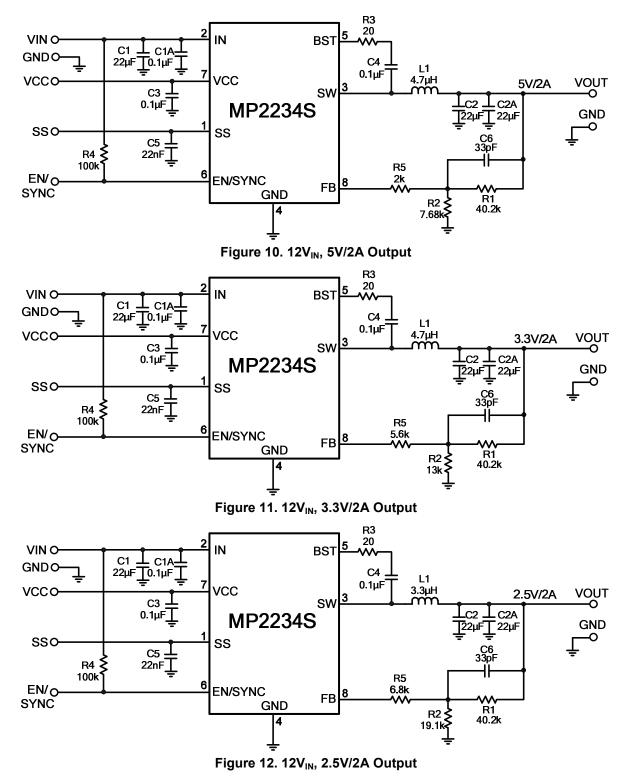
V <sub>IN</sub>	12V
V <sub>OUT</sub>	3.3V
Ι <sub>ουτ</sub>	2A

The detailed application schematic is shown in Figure 11. The typical performance and circuit waveforms have been shown in the Typical Performance Characteristics section. For more device applications, please refer to the related Evaluation Board Datasheets.



# **TYPICAL APPLICATION CIRCUITS**

mps





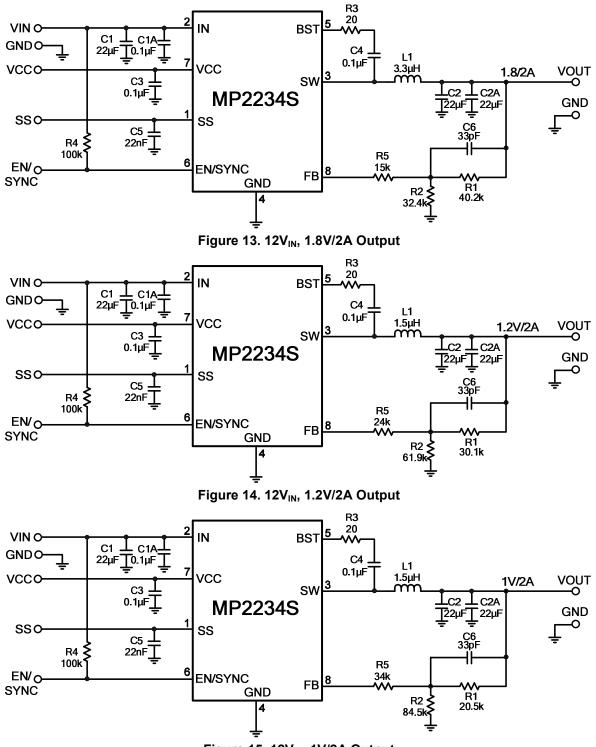
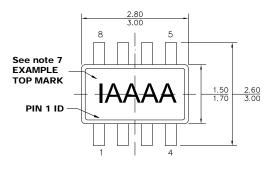


Figure 15. 12V<sub>IN</sub>, 1V/2A Output

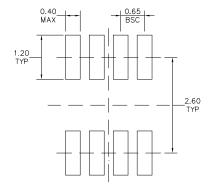


# PACKAGE INFORMATION

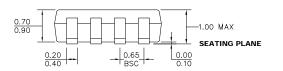
**TSOT23-8** 



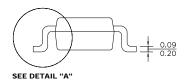
**TOP VIEW** 



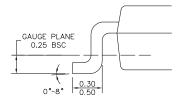
#### **RECOMMENDED LAND PATTERN**



FRONT VIEW



#### SIDE VIEW



DETAIL "A"

### NOTE:

 ALL DIMENSIONS ARE IN MILLIMETERS.
 PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURR.
 PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION.
 LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.10 MILLIMETERS MAX.
 JEDEC REFERENCE IS MO-193, VARIATION BA.
 DRAWING IS NOT TO SCALE.
 PIN 1 IS LOWER LEFT PIN WHEN READING TOP MARK FROM LEFT TO RIGHT, (SEE EXAMPLE TOP MARK)

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