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## INTEGRATED CIRCUITS



Product specification Supersedes data of 1997 Sep 02 File under Integrated Circuits, IC12 1999 Jan 06



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## **1 FEATURES**

- Operating supply voltage 2.5 to 6.0 V
- Low data retention voltage; minimum 1.0 V
- Low standby current; maximum 15 μA
- Power-saving mode; typical 50 nA
- Serial input/output bus (I<sup>2</sup>C-bus)
- Address by 3 hardware address pins
- Automatic word address incrementing
- Available in DIP8 and SO8 packages.

### 2 APPLICATIONS

- Telephony:
  - RAM expansion for stored numbers in repertory dialling (e.g. PCD33xxA applications)
- General purpose RAM for applications requiring extremely low current and low-voltage RAM retention, such as battery or capacitor-backed.
- Radio, television and video cassette recorder:
  - channel presets
- · General purpose:
  - RAM expansion for the microcontroller families PCD33xxA, PCF84CxxxA, P80CLxxx and most other microcontrollers.

### 4 QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>DD</sub>	supply voltage		2.5	6.0	
I <sub>DD</sub>	supply current (standby)	f <sub>SCL</sub> = 0 Hz	-	15	μA
I <sub>DDR</sub>	supply current (power-saving mode)	T <sub>amb</sub> = 25 °C	_	400	nA
T <sub>amb</sub>	operating ambient temperature		-40	+85	°C
T <sub>stg</sub>	storage temperature		-65	+150	°C

#### 5 ORDERING INFORMATION

ТҮРЕ	PACKAGE						
NUMBER	NAME	NAME DESCRIPTION VE					
PCF8570P	DIP8	plastic dual in-line package; 8 leads (300 mil)	SOT97-1				
PCF8570T	SO8	plastic small outline package; 8 leads; body width 7.5 mm	SOT176-1				



## 3 GENERAL DESCRIPTION

The PCF8570 is a low power static CMOS RAM, organized as 256 words by 8-bits.

Addresses and data are transferred serially via a two-line bidirectional bus (I<sup>2</sup>C-bus). The built-in word address register is incremented automatically after each written or read data byte. Three address pins, A0, A1 and A2 are used to define the hardware address, allowing the use of up to 8 devices connected to the bus without additional hardware.

## 6 BLOCK DIAGRAM



## 7 PINNING

SYMBOL	PIN	DESCRIPTION
A0	1	hardware address input 0
A1	2	hardware address input 1
A2	3	hardware address input 2
V <sub>SS</sub>	4	negative supply
SDA	5	serial data input/output
SCL	6	serial clock input
TEST	7	Input for power-saving mode (see section "Power-saving mode"). Also used as a test output during manufacture. TEST should be tied to V <sub>SS</sub> during normal operation.
V <sub>DD</sub>	8	positive supply



### Product specification

## $256\times8\text{-bit}$ static low-voltage RAM with I²C-bus interface

### 8 CHARACTERISTICS OF THE I<sup>2</sup>C-BUS

The I<sup>2</sup>C-bus is for bidirectional, two-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor. Data transfer may be initiated only when the bus is not busy.

#### 8.1 Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse as changes in the data line at this time will be interpreted as a control signal.



### 8.2 Start and stop conditions

Both data and clock lines remain HIGH when the bus is not busy. A HIGH-to-LOW transition of the data line, while the clock is HIGH is defined as the start condition (S). A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the stop condition (P).



## $256 \times 8$ -bit static low-voltage RAM with I<sup>2</sup>C-bus interface

### 8.3 System configuration

A device generating a message is a 'transmitter', a device receiving a message is the 'receiver'. The device that controls the message is the 'master' and the devices which are controlled by the master are the 'slaves'.



#### 8.4 Acknowledge

The number of data bytes transferred between the start and stop conditions from transmitter to receiver is unlimited. Each byte of eight bits is followed by an acknowledge bit. The acknowledge bit is a HIGH level signal put on the bus by the transmitter during which time the master generates an extra acknowledge related clock pulse. A slave receiver which is addressed must generate an acknowledge after the reception of each byte. Also a master receiver must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges must pull down the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse (set-up and hold times must be taken into consideration). A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event the transmitter must leave the data line HIGH to enable the master to generate a stop condition.



### 8.5 I<sup>2</sup>C-bus protocol

Before any data is transmitted on the I<sup>2</sup>C-bus, the device which should respond is addressed first. The addressing is always carried out with the first byte transmitted after the start procedure. The I<sup>2</sup>C-bus configuration for the different PCF8570 WRITE and READ cycles is shown in Figs 7, 8 and 9.







## 9 LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
V <sub>DD</sub>	supply voltage (pin 8)	-0.8	+8.0	V
VI	input voltage (any input)	-0.8	V <sub>DD</sub> + 0.8	V
l <sub>l</sub>	DC input current	-	±10	mA
I <sub>O</sub>	DC output current	-	±10	mA
I <sub>DD</sub>	positive supply current	-	±50	mA
I <sub>SS</sub>	negative supply current	-	±50	mA
P <sub>tot</sub>	total power dissipation per package	_	300	mW
Po	power dissipation per output	-	50	mW
T <sub>amb</sub>	operating ambient temperature	-40	+85	°C
T <sub>stg</sub>	storage temperature	-65	+150	°C

### 10 HANDLING

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take precautions appropriate to handling MOS devices. Advice can be found in Data Handbook IC12 under *"Handling MOS Devices"*.

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## 11 DC CHARACTERISTICS

 $V_{DD}$  = 2.5 to 6.0 V;  $V_{SS}$  = 0 V;  $T_{amb}$  = –40 to +85 °C; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply	1		ł		•	ł
V <sub>DD</sub>	supply voltage		2.5	-	6.0	V
I <sub>DD</sub>	supply current					
	standby mode	$\label{eq:VI} \begin{array}{l} V_{I} = V_{DD} \text{ or } V_{SS}; \\ f_{SCL} = 0 \text{ Hz}; \\ T_{amb} = -25 \text{ to } +70 \ ^{\circ}\text{C} \end{array}$	-	-	5	μA
	operating mode	$V_{I} = V_{DD} \text{ or } V_{SS};$ $f_{SCL} = 100 \text{ Hz}$	-	_	200	μA
V <sub>POR</sub>	Power-on reset voltage	note 1	1.5	1.9	2.3	V
Inputs, inp	out/output SDA					
V <sub>IL</sub>	LOW level input voltage	note 2	-0.8	-	0.3V <sub>DD</sub>	V
V <sub>IH</sub>	HIGH level input voltage	note 2	0.7V <sub>DD</sub>	-	V <sub>DD</sub> + 0.8	V
I <sub>OL</sub>	LOW level output current	V <sub>OL</sub> = 0.4 V	3	-	-	mA
I <sub>LI</sub>	input leakage current	$V_{I} = V_{DD} \text{ or } V_{SS}$	-1	-	+1	μA
Inputs A0,	, A1, A2 and TEST					
ILI	input leakage current	$V_{I} = V_{DD} \text{ or } V_{SS}$	-250	-	+250	nA
Inputs SC	L and SDA	·		·	·	
Ci	input capacitance	$V_{I} = V_{SS}$	-	_	7	pF
Low V <sub>DD</sub> d	lata retention		•	•		
V <sub>DDR</sub>	supply voltage for data retention		1	-	6	V
I <sub>DDR</sub>	supply current	V <sub>DDR</sub> = 1 V	-	-	5	μA
		V <sub>DDR</sub> = 1 V; T <sub>amb</sub> = -25 to +70 °C	-	-	2	μA
Power-sav	ving mode (see Figs 13 and 14)					
I <sub>DDR</sub>	supply current	TEST = V <sub>DD</sub> ; T <sub>amb</sub> = 25 °C	-	50	400	nA
t <sub>HD2</sub>	recovery time		_	50	-	μs
						I

#### Notes

1. The Power-on reset circuit resets the  $l^2$ C-bus logic when  $V_{DD} < V_{POR}$ . The status of the device after a Power-on reset condition can be tested by sending the slave address and testing the acknowledge bit.

2. If the input voltages are a diode voltage above or below the supply voltage  $V_{DD}$  or  $V_{SS}$  an input current will flow; this current must not exceed ±0.5 mA.

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## **12 AC CHARACTERISTICS**

All timing values are valid within the operating supply voltage and ambient temperature range and reference to  $V_{IL}$  and  $V_{IH}$  with an input voltage swing of  $V_{SS}$  to  $V_{DD}$ .

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT			
I <sup>2</sup> C-bus tim	<sup>2</sup> C-bus timing (see Fig.10; note 1)							
f <sub>SCL</sub>	SCL clock frequency	_	-	100	kHz			
t <sub>SP</sub>	tolerable spike width on bus	_	_	100	ns			
t <sub>BUF</sub>	bus free time	4.7	_	-	μs			
t <sub>SU;STA</sub>	START condition set-up time	4.7	_	-	μs			
t <sub>HD;STA</sub>	START condition hold time	4.0	_	-	μs			
t <sub>LOW</sub>	SCL LOW time	4.7	_	-	μs			
t <sub>HIGH</sub>	SCL HIGH time	4.0	_	-	μs			
t <sub>r</sub>	SCL and SDA rise time	_	_	1.0	μs			
t <sub>f</sub>	SCL and SDA fall time	_	_	0.3	μs			
t <sub>SU;DAT</sub>	data set-up time	250	_	-	ns			
t <sub>HD;DAT</sub>	data hold time	0	_	-	ns			
t <sub>VD;DAT</sub>	SCL LOW-to-data out valid	_	_	3.4	μs			
t <sub>SU;STO</sub>	STOP condition set-up time	4.0	_	_	μs			

### Note

1. A detailed description of the l<sup>2</sup>C-bus specification, with applications, is given in brochure "*The l<sup>2</sup>C-bus and how to use it*". This brochure may be ordered using the code 9398 393 40011.



## **13 APPLICATION INFORMATION**

## 13.1 Application example



## PCF8570

## 13.2 Slave address

The PCF8570 has a fixed combination 1 0 1 0 as group 1, while group 2 is fully programmable (see Fig.12).



### 13.3 Power-saving mode

With the condition TEST =  $V_{DD}$  or  $V_{DDR}$  the PCF8570 goes into the power-saving mode and I<sup>2</sup>C-bus logic is reset.



## + 5 V ▶ + $V_{\text{DD}}$ 8 SDA A2 5 3 V<sub>DDR</sub> SCL A1 6 PCF8570 2 1.2 V (NiCd) MICROCONTROLLER TEST<sup>(1)</sup> A0 7 1 4 V<sub>SS</sub> MLB933 777 It is recommended that a 4.7 $\mu\text{F}/10$ V solid aluminium capacitor (SAL) be connected between V\_{DD} and V\_{SS}. (1) In the operating mode TEST = 0 V; in the power-saving mode TEST = $V_{DDR}$ . Fig.14 Application example for power-saving mode.

## 14 PACKAGE OUTLINES

## DIP8: plastic dual in-line package; 8 leads (300 mil)



UNIT	A max.	A <sub>1</sub> min.	A <sub>2</sub> max.	b	b <sub>1</sub>	b <sub>2</sub>	с	D <sup>(1)</sup>	E <sup>(1)</sup>	е	e <sub>1</sub>	L	ME	м <sub>н</sub>	w	Z <sup>(1)</sup> max.
mm	4.2	0.51	3.2	1.73 1.14	0.53 0.38	1.07 0.89	0.36 0.23	9.8 9.2	6.48 6.20	2.54	7.62	3.60 3.05	8.25 7.80	10.0 8.3	0.254	1.15
inches	0.17	0.020	0.13	0.068 0.045	0.021 0.015	0.042 0.035	0.014 0.009	0.39 0.36	0.26 0.24	0.10	0.30	0.14 0.12	0.32 0.31	0.39 0.33	0.01	0.045

#### Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN ISSUE DATE			
VERSION	IEC	JEDEC	EIAJ		PROJECTION	1550E DATE
SOT97-1	050G01	MO-001AN				<del>-92-11-17</del> 95-02-04

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## $256\times8\text{-bit}$ static low-voltage RAM with I<sup>2</sup>C-bus interface

#### SO8: plastic small outline package; 8 leads; body width 7.5 mm SOT176-1 D А Х у $\Box$ = v 🕅 A $H_{E}$ 8 5 Q (A<sub>3</sub>) A<sub>1</sub> pin 1 index 1 Г 4 detail X • († w (M) е bp 0 5 10 mm scale DIMENSIONS (inch dimensions are derived from the original mm dimensions) Α Z<sup>(1)</sup> D<sup>(1)</sup> E<sup>(1)</sup> UNIT A<sub>1</sub> A<sub>2</sub> A<sub>3</sub> bp с е ${\sf H}_{\sf E}$ L Lp Q v w у θ max 2.45 0.49 10.65 2.0 0.3 0.32 7.65 7.6 1.1 1.1 mm 2.65 0.25 1.27 1.45 0.25 0.25 0.1 2.25 0.36 0.23 7.45 7.4 10.00 0.45 1.0 1.8 0.1 8° 0° 0.079 0.012 0.096 0.019 0.013 0.30 0.30 0.419 0.043 0.043 0.004 0.10 0.01 0.050 0.057 0.01 0.01 inches 0.004 0.089 0.014 0.009 0.29 0.29 0.394 0.018 0.039 0.071 Note 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included. REFERENCES OUTLINE EUROPEAN ISSUE DATE VERSION PROJECTION IEC JEDEC EIAJ 95-02-25 $\square$ SOT176-1 97-05-22

## $256 \times 8$ -bit static low-voltage RAM with I<sup>2</sup>C-bus interface

### 15 SOLDERING

#### 15.1 Introduction

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *"Data Handbook IC26; Integrated Circuit Packages"* (document order number 9398 652 90011).

There is no soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and surface mount components are mixed on one printed-circuit board. However, wave soldering is not always suitable for surface mount ICs, or for printed-circuit boards with high population densities. In these situations reflow soldering is often used.

#### 15.2 Through-hole mount packages

#### 15.2.1 SOLDERING BY DIPPING OR BY SOLDER WAVE

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joints for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ( $T_{stg(max)}$ ). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

#### 15.2.2 MANUAL SOLDERING

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

#### 15.3 Surface mount packages

#### 15.3.1 REFLOW SOLDERING

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, infrared/convection heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method. Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferable be kept below 230 °C.

#### 15.3.2 WAVE SOLDERING

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
  - larger than or equal to 1.27 mm, the footprint longitudinal axis is preferred to be parallel to the transport direction of the printed-circuit board;
  - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

• For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

#### 15.3.3 MANUAL SOLDERING

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to  $300 \,^{\circ}$ C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320  $^\circ\text{C}.$ 

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## 15.4 Suitability of IC packages for wave, reflow and dipping soldering methods

MOUNTING	PACKAGE	SOLDERING METHOD				
MOUNTING	PACKAGE	WAVE	REFLOW <sup>(1)</sup>	DIPPING		
Through-hole mount	DBS, DIP, HDIP, SDIP, SIL	suitable <sup>(2)</sup>	-	suitable		
Surface mount	BGA, SQFP	not suitable	suitable	_		
	HLQFP, HSQFP, HSOP, HTSSOP, SMS	not suitable <sup>(3)</sup>	suitable	_		
	PLCC <sup>(4)</sup> , SO, SOJ	suitable	suitable	_		
	LQFP, QFP, TQFP	not recommended <sup>(4)(5)</sup>	suitable	_		
	SSOP, TSSOP, VSO	not recommended <sup>(6)</sup>	suitable	_		

### Notes

- 1. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- 2. For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.
- 3. These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- 4. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- 5. Wave soldering is only suitable for LQFP, QFP and TQFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- 6. Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

# $256 \times 8$ -bit static low-voltage RAM with I<sup>2</sup>C-bus interface

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## **16 DEFINITIONS**

Data sheet status					
Objective specification	This data sheet contains target or goal specifications for product development.				
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.				
Product specification	This data sheet contains final product specifications.				
Limiting values					
more of the limiting values of the device at these or at	accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or nay cause permanent damage to the device. These are stress ratings only and operation any other conditions above those given in the Characteristics sections of the specification imiting values for extended periods may affect device reliability.				
Application information					
Where application information is given, it is advisory and does not form part of the specification.					

### 17 LIFE SUPPORT APPLICATIONS

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips for any damages resulting from such improper use or sale.

### 18 PURCHASE OF PHILIPS I<sup>2</sup>C COMPONENTS



Purchase of Philips I<sup>2</sup>C components conveys a license under the Philips' I<sup>2</sup>C patent to use the components in the I<sup>2</sup>C system provided the system conforms to the I<sup>2</sup>C specification defined by Philips. This specification can be ordered using the code 9398 393 40011.

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NOTES

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